Interesting the content of the fine former to 2 certification of the color of the c	Total Degrees of Freedom 22 22-45	Thickness (Stand)		
Total Degrees of Freedom Single Leg Degrees of Freedom Waist Degrees of Freedom 1	Total Degrees of Freedom Single Lay Degrees of Freedom Wast Degrees of Freedom 1		690x450x300mm	690x450x300mm
Single Log Degrees of Freedom Waist Degrees of Freedom Single Ixm Degrees of Freedom J Greedom J Single Ixm Degrees of Freedom J J Greedom J G G G G G G G G G G G G	Single Log Degrees of Freedom 6	Weight (With Battery)	About 35kg	About 35kg+
Prevention 1 Int Digition of 2 additional week degrees of freedom 1 Int Digition of 2 additional week degrees of freedom 5 5 5	Most Degrees of Freedom 1			23~43
Single Hond Degrees of Freedom Single Hond Degrees of Freedom J	Single Hand Degrees of Freedom Single Hand Degrees of Freedom			
Infection, the index finger has 2 extrine agrees. It becomes the technique make finger has 2 extrine agrees, the technique make finger has 2 extrem depress where the index finger has 2 extrem depress where a range. Maximum Torque of Knee Joint 10 Arm Maximum Lood 121 About 2/g Alexat 3/g Colf - Thigh Length Out Arm Spon About 0.45M Wass peet 2.1555* Knee pert 0.1455* Knee	Interest	Waist Degrees of Freedom		
Infection, the index finger has 2 extrine agrees. It becomes the technique make finger has 2 extrine agrees, the technique make finger has 2 extrem depress where the index finger has 2 extrem depress where a range. Maximum Torque of Knee Joint 10 Arm Maximum Lood 121 About 2/g Alexat 3/g Colf - Thigh Length Out Arm Spon About 0.45M Wass peet 2.1555* Knee pert 0.1455* Knee	Interest			
Knee Joint [1] Am Moximum Load [2] About 2/g About 2/g About 2/g About 2/g About 2/g About 2/d Am Spon About 0 45M About 0 4	Am Maximum Lood 121 About 2kg About 2kg About 1kg Coff + Thigh Length OAM About 0.45M About 0.45M About 1kg Extra Longe Joint West plant 2-155* Keep ort 0-155* High parts 2-155* High parts 2			hand) *2(Optional 2 additional wrist degrees of freedom) *Three-fingered dexterous hand Dex3-1 Parameter: The thumb has 3 active degrees of freedom, the index finger has 2 active degrees of freedom; the middle finger has 2 active degrees of freedom; at the middle finger has 2 active degrees of freedom; at the middle finger has 2 active degrees of freedom.
Colf - Thigh Length Arm Spon About 0.45M Arm Spon About 0.45M Weis John: Zu156*, Xu45*, Yu50* Kee john: D-166*, Noe john: C-166*, Noe john	Colf + Thigh Length Arm Spon About 0.45M Arm Spon About 0.45M Battra Lorge Joint Movement Space Ispanit: 2-155** Move part 0-165* Move part 0-165* Movement Space Ispanit: 2-155* Move part 0-165* Move part 1-165* Move part 0-165* Move part 0-165* Move part 1-165* Move p		90N.m	120N.m
Arm Span About 0.45M About 0.45M About 0.45M Extra Large Joint Movement Space Page 12 - 1455* Kee Joint Joint Hollow He Joint Pals4*, R.50+170*, Ya159* Full Joint Hollow Electrical Routing Joint Encoder Dual encoder Cooling System Local dir cooling Local dir cooling Local dir cooling Power Supply 13 string lithium battery 13 string lithium battery 8 series high-performance CPU 8 score high-performance CPU 8 score high-performance CPU Sensing Sensor Depth Comera-50 LIDAR Depth Comera-50 LIDAR 4 Microphone Array YES YES WIFI 6, Bluetooth 5.2 YES YES Power Moduler J Sonard Battery (Quick Release) Charger Set SA Set SA Set SA Manual Controller YES YES Warranty Period E41 8 months 1 year 10 The maximum tarque of the part macters of the whole modure is different. This is the maximum tarque of the largest pinet motor omong them. 13 for more distributed among home, place mod for great waters or package in motor omong them. 13 for more distributed among home, place mod filtered area schemos populars. 14 for more distributed among home, place mod filtered area schemos populars. 15 for more information, places and the schemosing browner transual. 14 for more distributed among them, place mod filtered among the backets watered proclaves. 15 The sharped of filtered schemos house. 15 The harmonical foliation is complex situature and externety poorer full grower. Libers are a subfactor solf distorce between the humanoid relaction.	Arm Spon About 0.45M Acout 0.45M About 0.45M Estro Longs Joint Movement Space Rep port: P-155" Keep port: 0-165" Rep port: P-154", R-30170", Y-156* Rep port	Arm Maximum Load [2]	About 2Kg	About 3Kg
Extra Large Joint Movement Space Wast part: 27155" Knee joint: 0165" Hip joint: 27155" Knee joint: 0165" Hip joint: 10165" Hip joint: 101	Extra Large Joint Movement Space Extra Large Joint Movement Space Wood plant: Za155° Knee Joint: Ca155° Knee Joint: Za155° Knee Joint: Ca155° Knee Joint: Ca155° Knee Joint: P154*, R 30-170°, Ya158* Will Joint Hollow Blectrical Routing YES YES	Calf + Thigh Length	0.6M	0.6M
Extra Large Joint Knoe joint: 1-165* Hip joint: 1-165*	Bette Large Joint Movement Space M	Arm Span	About 0.45M	About 0.45M
Description	Bectrical Routing YES YES		Knee joint: 0~165°	Knee joint: 0~165° Hip joint: P±154°、R-30~+170°、Y±158°
Cooling System Local air cooling Power Supply 13 string lithium bottery 15 string lithium bottery Basic Computing Power 8 core high-performance CPU 8-core high-performance CPU Sensing Sensor Depth Comero-5D LDAR Depth Comero-5D LDAR WES YES YES WIFI 6 . Bluetcoth 5.2 YES YES Wifi 6 . Bluetcoth 5.2 YES Wifi 6 . Bluetcoth 5.2 YES YES YES Warranty Power Module About 2h About 2h About 2h About 2h VES YES VES Warranty Period [4] 8 months 1 year II he maximum torque of the post motors of the whole modine is different. This is the maximum torque of the largest joint motor canong them. 2) The maximum torque of the post motors of the whole modine is different. This is the maximum torque of the largest joint motor canong them. 2) The maximum torque of the post motors of the whole modine is different to meanum, and all the maximum torque of the largest joint motor canong them. 2) The maximum torque of the post motors of the whole modine is additionable. 3) For more information, please read the secondary divelopment amounts. 4) For more detailed exementy terms, please read the secondary divelopment produce. 3) The humanood robot has a complex structure and estimally powerful power. Users one alked to keep to sufficient safe distance between the humanood robot has been and reader and a complex structure and estimally powerful power. Users one alked to keep to sufficient safe distance between the humanood robot has been and the safe and the power to maximum power and the power and the safe and	Cooling System Local dir cooling Local dir cooling		YES	
Power Supply 13 string lithrum bottery 14 string lithrum bottery 15 string lithrum bottery 15 string lithrum bottery 16 score high-performance CPU 17 Sensing Sensor Depth Comero+30 LIDAR PES WiFi 6 . Bluetooth 5.2 YES Word Adduct Northum Adduc	Power Supply 13 string lithrum battery 13 string lithrum battery	Joint Encoder	Dual encoder	Dual encoder
### Afficial Period [4] ### Afficial Period Intelligent OTA YES YES ### Warranty Period [4] ### months 1 year	A Microphone Array YES YES WiFi 6	Cooling System	Local air cooling	Local air cooling
### Afficial Period [4] ### Afficial Period Intelligent OTA YES YES ### Warranty Period [4] ### months 1 year	A Microphone Array YES YES WiFi 6	Power Supply	13 string lithium battery	13 string lithium battery
### Afficial Period [4] ### Afficial Period Intelligent OTA YES YES ### Warranty Period [4] ### months 1 year	A Microphone Array YES YES WiFi 6	Basic Computing Power	8-core high-performance CPU	8-core high-performance CPU
SW Speaker YES WiFi 6 . Bluetooth 5.2 YES YES YES High Computing	SW Speaker WIFI 6 . Bluetoath 5.2 YES YES WIFI 6 . Bluetoath 5.2 YES YES High Computing	Sensing Sensor	Depth Camera+3D LiDAR	Depth Camera+3D LiDAR
WiFi 6 . Bluetooth 5.2 WiFi 7 . Bluetooth 5.2 WiFi 8 . Bluetooth 5.4 WiFi 8	WiFi 6 . Bluetooth 5.2 YES WiFi 6 . Bluetooth 5.2 YES YES NVIDIA Jetson Orin NVIDI	4 Microphone Array	YES	
High Computing Power Module Smart Battery (Quick Release) 9000mAh 9000mAh Charger 5-4V 5A 5-6V 5A Manual Controller YES YES Battery Life About 2h About 2h Lipgraded Intelligent OTA YES YES Secondary Development [3] I YES Warranty Period [4] 8 months 1 year 11 The maximum torque of the joint motors of the whole moduline is different. This is the maximum torque of the largest joint motor among them. [2] The maximum torque of the joint motors of the whole moduline is different. This is the maximum torque of the largest joint motor among them. [3] For more information, please read the secondary development manual. [4] For more detailed warranty terms, please read the product warranty brothure. [5] The bother parameters may vary in different somerons and configurations, please subject to actual situation. [6] The humanoid robot thesia a complex situature and extremely powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot Please use with caution.	High Computing Power Module Smart Battery (Quick Release) 9000mAh 9000mAh 9000mAh 9000mAh Charger 54V SA 54V SA Manual Controller YES WES Battery Life About 2h About 2h About 2h VES VES Wes Wes **The Manual Controller YES YES **The Manual Controller YES **The Manual Controller YES **The Manual Controller **	5W Speaker		
Power Module Smart Battery (Quick Release) Poolmah Charger Sat	Power Module Smart Battery (Quick Release) 9000mAh 9000mAh 9000mAh Charger S4V 5A S4V 5A Manual Controller YES WES Battery Life About 2h About 2h About 2h VES VES Secondary Development 131 J YES Warranty Period 141 8 months 1 year 10 The maximum torque of the joint meters of the whole modhine is different. This is the maximum torque of the largest joint meter among them. 2) The maximum boad of the corn varies greatly under different are extension postures. 3) For more information, please read the secondary development manual. 4) For more detailed warranty terms, please read the product warranty brodure. 5) The above parameters may vary in different scenarios and configurations, please subject to actual situation. 6) The humanoid sobot has a complex structure and externelly powerful powerful power. The obove parameters may vary in different scenarios and configurations, please subject to actual situation. 6) The humanoid sobot has a complex structure and externelly powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid ribbot the humanoid ribbot the humanoid ribbot to the product, please relief to the octual product. Till dray change in the appearance of the product, please refer to the octual product. Some sample functions on this page are still being developed and tested, and will be opened to users in the future.		YES	
Charger 5.4V SA 54V SA	Charger S4V SA S6V SA	Power Module		NVIDIA Jetson Orin
Manual Controller WES Battery Life About 2h About 2h Upgraded Intelligent OTA YES YES Secondary Development [3] I YES Warranty Period [4] 8 months 1 year 11 The maximum torque of the joint motors of the whole modhine is different. This is the maximum torque of the largest joint motor among them. [3] For more information, please read the secondary development manual. [4] For more information, please read the secondary development manual. [5] The above parameters may vary in different someons and configurations, please subject to actual situation. [6] The humanoid robot has a complex structure and extremely powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot Please use with caution.	Manual Controller WES Battery Life About 2h About 2h VES VES VES Secondary Development 151 Warranty Period 141 8 months 1 year 11 The maximum tarque of the joint motors of the whole modinie is different. This is the maximum tarque of the largest joint motor among them. 12) The maximum tarque of the joint motors of the whole modinie is different. This is the maximum tarque of the largest joint motor among them. 12) The maximum barque of the joint motors of the whole modinie is different. This is the maximum tarque of the largest joint motor among them. 13) For more information, places read the secondary development monus. 14) For more detailed warranty terms, places end the product warranty brochure. 15) The obove parameters may vary in different scenarios and configurations, please subject to actual situation. 16) The humanoid robot has a complex structure and externelly power if power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot may be in the appearance of the product, please refer to the actual product. 18) Some change in the appearance of the product, please refer to the actual product. 18) Some change in the appearance of the product, please refer to the actual product. 18) Some change in the appearance of the product, please refer to the actual product. 18) Some change in the appearance of the product, please refer to the actual product.		9000mAh	9000mAh
Bottery Life About 2h Upgraded Intelligent OTA YES YES Secondary Development [3] I YES Warranty Period [4] 8 months 1 year 1) The maximum torque of the joint motors of the whole modhine is different. This is the maximum torque of the largest joint motor among them. 2) The maximum torque of the joint motors of the whole modhine is different. This is the maximum torque of the largest joint motor among them. 2) The maximum load of the own varies greatly under different are extension postures. 3) For more information, please read the secondary development manual. 4) For more detailed warranty terms, please read the product warranty brothure. (3) The butwee parameters may vary in different scenarios and configurations, please subject to actual situation. (4) The humanoid robot has a complex structure and extremely powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot Please use with caution.	Bottery Life About 2h YES Upgraded Intelligent OTA YES YES Secondary Development 131 I YES Warranty Period [4] 8 months 1 year [1] The maximum torque of the joint motors of the whole machine is different. This is the maximum torque of the largest joint motor among them. [2] The maximum board of the orm varies greatly under different arm extension postures. [3] For more information, places read the secondary divelopment monual. [4] For more detailed warranty termin, please read the product warranty brodhure. [5] The above parameters may vary in different scenarios and configurations, please subject to actual situation. [6] The humanoid stobet has complex structures and externelly power full power, bleas are asked to keep a sufficient safe distance between the humanoid robot the humanoid mbbc Please use with causion [7] If any change in the appearance of the product, please refer to the actual product. [8] Some sample functions on this page are still being developed and tested, and will be opened to users in the future.	Charger	54V 5A	54V SA
Upgraded Intelligent OTA YES YES Secondary Development [3] I YES Warranty Period [4] 8 months 1 year 1] The maximum torque of the joint motors of the whole modhine is different. This is the maximum torque of the largest joint motor among them. 12) The maximum torque of the joint motors of the whole modhine is different. This is the maximum torque of the largest joint motor among them. 13) For more information, please read the secondary development morous. 14) For more electually warranty terms, please read the product warranty brochure. 15) The above parameters may vary in different scenarios and configurations, please subject to actual situation. 16) The humanoid robot has a complex structure and extremely powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot Please use with caution.	Upgraded Intelligent OTA YES YES Warranty Period [4] 8 months 1 year 1) The maximum torque of the joint motors of the whole modnine is different. This is the maximum torque of the largest joint motor among them. 2) The maximum bod of the arm varies greatly under different arm extension postures. [3] For more information, please read the secondary development manual. [4] For more detailed warranty terms, please read the product warranty brodure. [5] The above parameters may vary in different seconds and configurations, please subject to actual situation. [6] The humanoid robot has a complex situature and externelly powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot does not preciously an externel powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot appearance of the product, please refer to the actual product. [8] Some sample functions on this page are still being developed and tested, and will be opened to users in the future.	Manual Controller		
Secondary Development [3] Warranty Period [4] 8 months 1 year [1] The maximum torace of the joint motors of the whole mochine is different. This is the maximum torace of the largest joint motor among them. [2] The maximum load of the arm varies greatly under different arm extension postures. [3] For more information, pieces read the secondary development morus. [4] For more detailed warranty terms, please read the product warranty brochure. [5] The above parameters may vary in different scenarios and configurations, pieces subject to actual situation. [6] The humanoid robot has a complex structure and extremely powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot Pieces use with caution.	Secondary Development [3] Warranty Period [4] 8 months 1 year [1] The maximum torque of the joint motors of the whole modnine is different. This is the maximum torque of the largest joint motor among them. [2] The maximum load of the arm varies greatly under different arm extension postures. [3] For more information, please read the secondary development manual. [4] For more detailed warranty terms, please read the product warranty brochure. [5] The above parameters may vary in different scenarios and configurations, please subject to actual situation. [6] The humanoid oboit has a complex structure and externelly powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot the humanoid robot the humanoid robot appearance of the product, please refer to the actual product. [8] Some sample functions on this page are still being developed and tested, and will be opened to users in the future.	Battery Life	About 2h	About 2h
Warranty Period [4] & months 1 year [1] The maximum torque of the joint motors of the whole modhine is different. This is the maximum torque of the largest joint motor among them. [2] The maximum load of the arm varies greatly under different arm extension postures. [3] For more information, please read the secondary development manual. [4] For more detailed warranty terms, please read the product warranty brochure. [5] The babove parameters may vary in different sciencinos and configurations, please subject to actual situation. [6] The humanoid robot has a complex situature and extremely powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot Pierose use with coultin.	Warranty Period [4] 8 months 1 year [1] The maximum torque of the joint motors of the whole modhine is different. This is the maximum torque of the largest joint motor among them. [2] The maximum boal of the arm varies greatly under different arm extension postures. [3] For more information, please read the secondary development manual. [4] For more detailed warranty terms, please read the product warranty brodume. [5] The above parameters may vary in different scenarios and configurations, please subject to actual situation. [6] The humanoid aboth thas a complex structure and externelly powerful power. Users are asked to keep a sufficient safe distance between the humanoid robot the humanoid robot dependence of the product, please refer to the actual product. [8] Some sample functions on this page are still being developed and tested, and will be opened to users in the future.	Upgraded Intelligent OTA		
		Secondary Development [3]		
		Warranty Period [4]	8 months	1 year
	end product a district mode, the strong request one of objects request from making any sungentius manner, and the report in a repair of a repair of the report in a re			

G1 EDU

Height, Width and Thickness (Stand)